



The network of Horizon Europe Cluster 5 National Contact Point.

Entity profiles linked to specific topics

Samra Sarwar - DeustoTech

samra.sarwar@deusto.es

GREENET Brokerage Event 6th May 2025





- Samra Sarwar, Research Associate
- DeustoTech, Research institute. Bilbao, Spain.
- Mobility and transport unit
 - Intelligent Transport systems
 - Cooperative communications
 - Artificial intelligence techniques
 - Positioning

Contact details:

- samra.sarwar@deusto.es
- http:\\research.mobility.deustotech.eu









HORIZON-CL5-2025-01-D6-11: Innovative air mobility and services for sustainable and smart urban, peri-urban transport – Societal Readiness pilot (RIA; 04/09/2025)

Our Contribution

- Advanced Urban Logistics Simulation Engine with:
- **Dynamic route optimization** Real-time adjustments for disruptions.
- Multi-modal & intermodal modeling Simulates drones, trucks, and hybrid transport.
- Logistics traffic density maps Predicts road usage by delivery vehicles (area/time-specific).

<u>Extension</u> → Innovative Air Mobility (IAM) cargo – Drone behavior modeling (travel time, energy, autonomy, restricted areas) for defining the delivery routes including the simulator's intermodality and multimodality capabilities to model.

Technology Profile



Multi-agent system + Energy/autonomy algorithms for drone route planning.

Experience & Relevance

Proven expertise in last-mile logistics simulation.





HORIZON-CL5-2025-01-D6-12: Safe Human-Technology Interaction (HTI) in the vehicle systems of the coming decade – Societal Readiness Pilot (IA; 04/09/2025)

Our Contribution

- Al-Algorithm Real-time detection of driver stress/distraction with multimodal information (in-vehicle sensors, wearables, traffic/weather).
- Generation of alerts based on the results of the previous algorithms. Co-design study of the type of alert to generate: sound, light, colour, duration, etc.

Technology Profile

Sensor Fusion + Al Algorithm

Experience

Participation in European Horizon projects.

Projects: (CONDUCTOR).





HORIZON-CL5-2026-01-D6-05: Approaches, verification and training for Edge-AI building blocks for CCAM Systems (CCAM Partnership) (RIA; 20/01/2026)

Our Contribution

- **Edge-Al Optimization** Adapting Al algorithms for embedded accelerators (Security operations center) to minimize latency/energy without compromising detection performance.
- Real-time traffic risk analysis On-device inference for risk detection (jaywalking, lane invasions by bicycles or scooters, and unsafe pedestrian crossings in multimodal intersections).

Technology Profile



Platforms - NVIDIA Jetson, Xilinx Kria, Google Coral.



Models - TrafficCamNet, YOLO variants + NvDCF tracking.



Optimizations - Quantization, pruning, edge TPU deployment.

Experience



Projects - CONDOR, PORTAERA (real-world validation).

